**Review.**

- The solution to $\boldsymbol{y}' = A\boldsymbol{y}$, $\boldsymbol{y}(0) = \boldsymbol{y}_0$ is $\boldsymbol{y}(t) = e^{At}\boldsymbol{y}_0$.
  **Why?** Because $\boldsymbol{y}'(t) = Ae^{At}\boldsymbol{y}_0 = A\boldsymbol{y}(t)$ and $\boldsymbol{y}(0) = e^{0A}\boldsymbol{y}_0 = \boldsymbol{y}_0$.
- If we have the diagonalization $A = PDP^{-1}$, then $e^A = Pe^DP^{-1}$ (and $e^{At} = Pe^{Dt}P^{-1}$).
- If $A = \begin{bmatrix} 2 & 0 \\ 0 & 5 \end{bmatrix}$, then $e^A = \begin{bmatrix} e^2 & 0 \\ 0 & e^5 \end{bmatrix}$ and $e^{At} = \begin{bmatrix} e^{2t} & 0 \\ 0 & e^{5t} \end{bmatrix}$.

**Comment.** We only discuss **linear** differential equations (DEs). **Non-linear** DEs include $y' = y^2 + 1$ or the second-order equation $y'' = \sin(ty') + y$. The **order** of a DE indicates the highest occuring derivative.
We will see here how to solve those linear DEs which have constant coefficients (for instance, $y'' = \sin(t)y' + y$ is linear but the coefficients include $\sin(t)$ which is not constant). That is, the coefficients of $y$ are constants, as opposed to functions (like $\sin(t)$) depending on $t$.

**Example 131.** Solve the initial value problem

$$\boldsymbol{y}' = \begin{bmatrix} 2 & 0 & 0 \\ -1 & 3 & 1 \\ -1 & 1 & 3 \end{bmatrix}\boldsymbol{y}, \qquad \boldsymbol{y}(0) = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}.$$

**Solution.** Recall that the solution to $\boldsymbol{y}' = A\boldsymbol{y}$, $\boldsymbol{y}(0) = \boldsymbol{y}_0$ is $\boldsymbol{y} = e^{At}\boldsymbol{y}_0$.

- First, we diagonalize:
  For $A = \begin{bmatrix} 2 & 0 & 0 \\ -1 & 3 & 1 \\ -1 & 1 & 3 \end{bmatrix}$, $A = PDP^{-1}$ with $P = \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}$ and $D = \begin{bmatrix} 2 & & \\ & 2 & \\ & & 4 \end{bmatrix}$. (That's homework!)
- We can then compute the solution $\boldsymbol{y}(t) = e^{At}\boldsymbol{y}_0$:

$$\begin{aligned} \boldsymbol{y}(t) = e^{At}\boldsymbol{y}_0 &= Pe^{Dt}P^{-1}\boldsymbol{y}_0 \\ &= \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}\begin{bmatrix} e^{2t} & & \\ & e^{2t} & \\ & & e^{4t} \end{bmatrix}\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}^{-1}\begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}\begin{bmatrix} e^{2t} & & \\ & e^{2t} & \\ & & e^{4t} \end{bmatrix}\begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} \\ &= \begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}\begin{bmatrix} e^{2t} \\ 0 \\ e^{4t} \end{bmatrix} = \begin{bmatrix} e^{2t} \\ e^{2t} + e^{4t} \\ e^{4t} \end{bmatrix} \end{aligned}$$

**Comment.** It is not necessary to compute $\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}^{-1}$ (of course, you could do it, but that's more work).
Instead, recall that $A^{-1}\boldsymbol{b}$ is the unique solution to $A\boldsymbol{x} = \boldsymbol{b}$. Here, solving $\begin{bmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 1 \end{bmatrix}\boldsymbol{x} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$, we find $\boldsymbol{x} = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$.

**Check.** $\boldsymbol{y} = \begin{bmatrix} e^{2t} \\ e^{2t} + e^{4t} \\ e^{4t} \end{bmatrix}$ indeed solves the original problem:

$$\boldsymbol{y}' = \begin{bmatrix} 2e^{2t} \\ 2e^{2t} + 4e^{4t} \\ 4e^{4t} \end{bmatrix} \stackrel{\checkmark}{=} \begin{bmatrix} 2 & 0 & 0 \\ -1 & 3 & 1 \\ -1 & 1 & 3 \end{bmatrix}\begin{bmatrix} e^{2t} \\ e^{2t} + e^{4t} \\ e^{4t} \end{bmatrix}, \qquad \boldsymbol{y}(0) = \begin{bmatrix} 1 \\ 1+1 \\ 1 \end{bmatrix} \stackrel{\checkmark}{=} \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}$$

Armin Straub
straub@southalabama.edu

**Example 132.** Solve the initial value problem $\boldsymbol{y}' = \begin{bmatrix} 0 & -2 \\ -1 & 1 \end{bmatrix} \boldsymbol{y}, \quad \boldsymbol{y}(0) = \begin{bmatrix} 3 \\ 0 \end{bmatrix}$.

**Solution.**

- $A = \begin{bmatrix} 0 & -2 \\ -1 & 1 \end{bmatrix}$ has characteristic polynomial $-\lambda(1-\lambda) - 2 = (\lambda+1)(\lambda-2)$.
  Hence, the eigenvalues of $A$ are $-1, 2$.
  The $-1$-eigenspace $\operatorname{null}\left(\begin{bmatrix} 1 & -2 \\ -1 & 2 \end{bmatrix}\right)$ has basis $\begin{bmatrix} 2 \\ 1 \end{bmatrix}$.
  The $2$-eigenspace $\operatorname{null}\left(\begin{bmatrix} -2 & -2 \\ -1 & -1 \end{bmatrix}\right)$ has basis $\begin{bmatrix} -1 \\ 1 \end{bmatrix}$.
  Hence, $A = PDP^{-1}$ with $P = \begin{bmatrix} 2 & -1 \\ 1 & 1 \end{bmatrix}$ and $D = \begin{bmatrix} -1 & \\ & 2 \end{bmatrix}$.
- Finally, we compute the solution $\boldsymbol{y}(t) = e^{At}\boldsymbol{y}_0$:

$$\begin{aligned} \boldsymbol{y}(t) &= Pe^{Dt}P^{-1}\boldsymbol{y}_0 \\ &= \underbrace{\begin{bmatrix} 2 & -1 \\ 1 & 1 \end{bmatrix}\begin{bmatrix} e^{-t} & \\ & e^{2t} \end{bmatrix}}_{\begin{bmatrix} 2e^{-t} & -e^{2t} \\ e^{-t} & e^{2t} \end{bmatrix}} \underbrace{\frac{1}{3}\begin{bmatrix} 1 & 1 \\ -1 & 2 \end{bmatrix}\begin{bmatrix} 3 \\ 0 \end{bmatrix}}_{\begin{bmatrix} 1 \\ -1 \end{bmatrix}} = \begin{bmatrix} 2e^{-t} + e^{2t} \\ e^{-t} - e^{2t} \end{bmatrix} \end{aligned}$$

**Check.** Since it is simple to check, it would be almost criminal to not verify that $\boldsymbol{y}(0) = \begin{bmatrix} 2+1 \\ 1-1 \end{bmatrix} = \begin{bmatrix} 3 \\ 0 \end{bmatrix}$.

## Higher-order differential equations

**Example 133.** Write the (second-order) differential equation $y'' = 2y' + y$ as a system of (first-order) differential equations.

**Solution.** Write $y_1 = y$ and $y_2 = y'$. Then $y'' = 2y' + y$ becomes $y_2' = 2y_2 + y_1$.

Therefore, $y'' = 2y' + y$ translates into the first-order system $\begin{cases} y_1' = y_2 \\ y_2' = y_1 + 2y_2 \end{cases}$.

In matrix form, this is $\boldsymbol{y}' = \begin{bmatrix} 0 & 1 \\ 1 & 2 \end{bmatrix}\boldsymbol{y}$.

**Comment.** Hence, we care about systems of differential equations, even if we work with just one function.

**Note.** The "trick" of looking at the pair $\begin{bmatrix} y \\ y' \end{bmatrix}$ instead of a single function is what we used to translate the Fibonacci recurrence into a $2\times 2$ system.

**Alternatively.** Instead of looking at the pair $\boldsymbol{y} = \begin{bmatrix} y \\ y' \end{bmatrix}$ we could also consider the pair $\boldsymbol{y} = \begin{bmatrix} y' \\ y \end{bmatrix}$. In the latter case, the system becomes $\boldsymbol{y}' = \begin{bmatrix} 2 & 1 \\ 1 & 0 \end{bmatrix}\boldsymbol{y}$. Either choice is fine and it makes no difference for the computations.

**Example 134.** Write the (third-order) differential equation $y''' = 3y'' - 2y' + y$ as a system of (first-order) differential equations.

**Solution.** Write $y_1 = y$, $y_2 = y'$ and $y_3 = y''$.

Then, $y''' = 3y'' - 2y' + y$ translates into the first-order system $\begin{cases} y_1' = y_2 \\ y_2' = y_3 \\ y_3' = y_1 - 2y_2 + 3y_3 \end{cases}$.

In matrix form, this is $\boldsymbol{y}' = \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & -2 & 3 \end{bmatrix}\boldsymbol{y}$.